

Additional Examples of Chapter 2: Discrete-Time Signals and Systems

Example E2.1: Analyze the block diagram of the LTI discrete-time system of Figure E2.1 and develop the relation between $y[n]$ and $x[n]$.

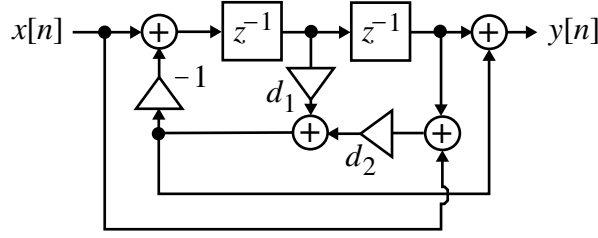
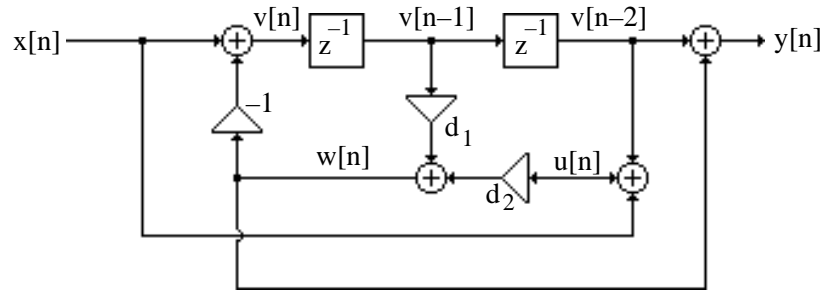


Figure E2.1

Answer: From the figure shown below we obtain



$v[n] = x[n] - w[n]$, $w[n] = d_1 v[n-1] + d_2 u[n]$, and $u[n] = v[n-2] + x[n]$. From these equations we get $w[n] = d_2 x[n] + d_1 x[n-1] + d_2 x[n-2] - d_1 w[n-1] - d_2 w[n-2]$. From the figure we also obtain $y[n] = v[n-2] + w[n] = x[n-2] + w[n] - w[n-2]$, which yields $d_1 y[n-1] = d_1 x[n-3] + d_1 w[n-1] - d_1 w[n-3]$, and $d_2 y[n-2] = d_2 x[n-4] + d_2 w[n-2] - d_2 w[n-4]$. Therefore,
 $y[n] + d_1 y[n-1] + d_2 y[n-2] = x[n-2] + d_1 x[n-3] + d_2 x[n-4]$
 $+ (w[n] + d_1 w[n-1] + d_2 w[n-2]) - (w[n-2] + d_1 w[n-3] + d_2 w[n-4])$
 $= x[n-2] + d_2 x[n] + d_1 x[n-1]$ or equivalently,
 $y[n] = d_2 x[n] + d_1 x[n-1] + x[n-2] - d_1 y[n-1] - d_2 y[n-2]$.

Example E2.2: The sequence $\{0 \quad -\sqrt{2} \quad -2 \quad -\sqrt{2} \quad 0 \quad \sqrt{2} \quad 2 \quad \sqrt{2}\}$ represents one period of a sinusoidal sequence $x[n] = A \sin(\omega_0 n + \phi)$. Determine the values of the parameters A , ω_0 , and ϕ .

Answer: Given $x[n] = \{0 \quad -\sqrt{2} \quad -2 \quad -\sqrt{2} \quad 0 \quad \sqrt{2} \quad 2 \quad \sqrt{2}\}$. The fundamental period is $N = 4$, hence $\omega_0 = 2\pi / 8 = \pi / 4$. Next from $x[0] = A \sin(\phi) = 0$ we get $\phi = 0$, and solving $x[1] = A \sin(\frac{\pi}{4} + \phi) = A \sin(\pi / 4) = -\sqrt{2}$ we get $A = -2$.

Additional Examples of Chapter 2: Discrete-Time Signals and Systems

Example E2.3: Determine the fundamental period of the periodic sequence $\tilde{x}[n] = \sin(0.6\pi n + 0.6\pi)$.

Answer: Here, $\omega_o = 0.6\pi$. From Eq. (2.47a), we thus get $N = \frac{2\pi r}{\omega_o} = \frac{2\pi r}{0.6\pi} = \frac{10}{3}r = 10$ for $r = 3$.

Example E2.4: Determine the fundamental period of the periodic sequence $\tilde{y}[n] = 3\sin(1.3\pi n) - 4\cos(0.3\pi n + 0.45\pi)$.

Answer: $N_1 = \frac{2\pi r_1}{1.3\pi} = \frac{20}{13}r_1$ and $N_2 = \frac{2\pi r_2}{0.3\pi} = \frac{20}{3}r_2$. To be periodic we must have $N_1 = N_2$. This implies, $\frac{20}{13}r_1 = \frac{20}{3}r_2$. This equality holds for $r_1 = 13$ and $r_2 = 7$, and hence $N = N_1 = N_2 = 20$.

Example E2.5: Let $\{y[n]\} = \{-1 \ -1 \ 11 \ -3 \ 30 \ 28 \ 48\}$ obtained by a linear convolution of the sequence $\{h[n]\} = \{-1 \ 2 \ 3 \ 4\}$ with a finite-length sequence $\{x[n]\}$. The first sample in each sequence is time instant $n = 0$. Determine $x[n]$.

Answer: The length of $x[n]$ is $7 - 4 + 1 = 4$. Using $x[n] = \frac{1}{h[0]} \left\{ y[n] - \sum_{k=1}^7 h[k]x[n-k] \right\}$ we arrive at $x[n] = \{1 \ 3 \ -2 \ 12\}$, $0 \leq n \leq 3$.

Example E2.6: Determine the expression for the impulse response of the LTI discrete-time system shown in Figure E2.2.

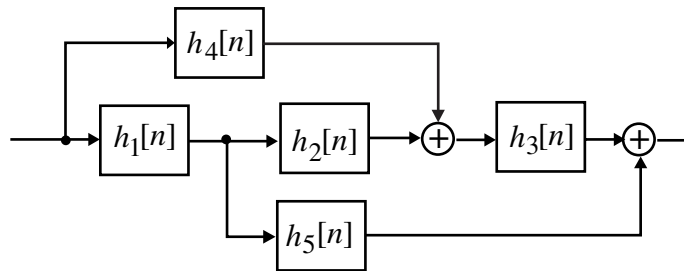
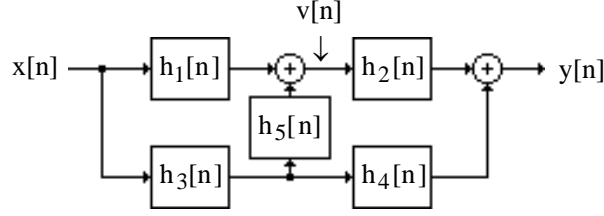


Figure E2.2

Answer: From the figure shown below we observe

Additional Examples of Chapter 2: Discrete-Time Signals and Systems



$$v[n] = (h_1[n] + h_3[n] \circledast h_5[n]) \circledast x[n] \text{ and } y[n] = h_2[n] \circledast v[n] + h_3[n] \circledast h_4[n] \circledast x[n].$$

$$\text{Thus, } y[n] = (h_2[n] \circledast h_1[n] + h_2[n] \circledast h_3[n] \circledast h_5[n] + h_3[n] \circledast h_4[n]) \circledast x[n].$$

Hence the impulse response is given by

$$h[n] = h_2[n] \circledast h_1[n] + h_2[n] \circledast h_3[n] \circledast h_5[n] + h_3[n] \circledast h_4[n].$$

Example E2.7: Determine the total solution for $n \geq 0$ of the difference equation

$$y[n] + 0.1y[n-1] - 0.06y[n-2] = 2^n \mu[n],$$

with the initial condition $y[-1] = 1$ and $y[-2] = 0$.

Answer: $y[n] + 0.1y[n-1] - 0.06y[n-2] = 2^n \mu[n]$ with $y[-1] = 1$ and $y[-2] = 0$. The complementary solution $y_c[n]$ is obtained by solving $y_c[n] + 0.1y_c[n-1] - 0.06y_c[n-2] = 0$.

To this end we set $y_c[n] = \lambda^n$, which yields

$$\lambda^n + 0.1\lambda^{n-1} - 0.06\lambda^{n-2} = \lambda^{n-2}(\lambda^2 + 0.1\lambda - 0.06) = 0 \text{ whose solution gives } \lambda_1 = -0.3 \text{ and } \lambda_2 = 0.2.$$

Thus, the complementary solution is of the form $y_c[n] = \alpha_1(-0.3)^n + \alpha_2(0.2)^n$.

For the particular solution we choose $y_p[n] = \beta(2)^n$. substituting this solution in the difference equation representation of the system we get $\beta 2^n + \beta(0.1)2^{n-1} - \beta(0.06)2^{n-2} = 2^n \mu[n]$. For $n = 0$ we get $\beta + \beta(0.1)2^{-1} - \beta(0.06)2^{-2} = 1$ or $\beta = 200 / 207 = 0.9662$.

The total solution is therefore given by $y[n] = y_c[n] + y_p[n] = \alpha_1(-0.3)^n + \alpha_2(0.2)^n + \frac{200}{207} 2^n$.

From the above $y[-1] = \alpha_1(-0.3)^{-1} + \alpha_2(0.2)^{-1} + \frac{200}{207} 2^{-1} = 1$ and

$$y[-2] = \alpha_1(-0.3)^{-2} + \alpha_2(0.2)^{-2} + \frac{200}{207} 2^{-2} = 0 \text{ or equivalently, } -\frac{10}{3} \alpha_1 + 5 \alpha_2 = \frac{107}{207} \text{ and}$$

$$\frac{100}{9} \alpha_1 + 25 \alpha_2 = -\frac{50}{207} \text{ whose solution yields } \alpha_1 = -0.1017 \text{ and } \alpha_2 = 0.0356. \text{ Hence, the total}$$

solution is given by $y[n] = -0.1017(-0.3)^n + 0.0356(0.2)^n + 0.9662(2)^n$, for $n \geq 0$.

Example E2.8: Determine the total solution for $n \geq 0$ of the difference equation

$$y[n] + 0.1y[n-1] - 0.06y[n-2] = x[n] - 2x[n-1],$$

with the initial condition $y[-1] = 1$ and $y[-2] = 0$, when the forcing function is $x[n] = 2^n \mu[n]$.

Additional Examples of Chapter 2: Discrete-Time Signals and Systems

Answer: $y[n] + 0.1y[n-1] - 0.06y[n-2] = x[n] - 2x[n-1]$ with $x[n] = 2^n \mu[n]$, and $y[-1] = 1$ and $y[-2] = 0$. For the given input, the difference equation reduces to $y[n] + 0.1y[n-1] - 0.06y[n-2] = 2^n \mu[n] - 2(2^{n-1})\mu[n-1] = \delta[n]$. The solution of this equation is thus the complementary solution with the constants determined from the given initial conditions $y[-1] = 1$ and $y[-2] = 0$.

From the solution of the previous problem we observe that the complementary solution is of the form $y_c[n] = \alpha_1(-0.3)^n + \alpha_2(0.2)^n$.

For the given initial conditions we thus have

$y[-1] = \alpha_1(-0.3)^{-1} + \alpha_2(0.2)^{-1} = 1$ and $y[-2] = \alpha_1(-0.3)^{-2} + \alpha_2(0.2)^{-2} = 0$. Combining these two equations we get $\begin{bmatrix} -1/0.3 & 1/0.2 \\ 1/0.09 & 1/0.04 \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ which yields $\alpha_1 = -0.18$ and $\alpha_2 = 0.08$.

Therefore, $y[n] = -0.18(-0.3)^n + 0.08(0.2)^n$.

Example E2.9: Determine the impulse response $h[n]$ of the LTI discrete-time system described by the difference equation

$$y[n] + 0.1y[n-1] - 0.06y[n-2] = x[n] - 2x[n-1].$$

Answer: The impulse response is given by the solution of the difference equation

$y[n] + 0.1y[n-1] - 0.06y[n-2] = \delta[n]$. From Example E2.7, the complementary solution is given by $y_c[n] = \alpha_1(-0.3)^n + \alpha_2(0.2)^n$. To determine the constants α_1 and α_2 , we observe $y[0] = 1$ and $y[1] + 0.1y[0] = 0$ as $y[-1] = y[-2] = 0$. From the complementary solution $y[0] = \alpha_1(-0.3)^0 + \alpha_2(0.2)^0 = \alpha_1 + \alpha_2 = 1$, and $y[1] = \alpha_1(-0.3)^1 + \alpha_2(0.2)^1 = -0.3\alpha_1 + 0.2\alpha_2 = -0.1$. Solution of these equations yields $\alpha_1 = 0.6$ and $\alpha_2 = 0.4$. Therefore, the impulse response is given by $h[n] = 0.6(-0.3)^n + 0.4(0.2)^n$.
