QP Code:601402

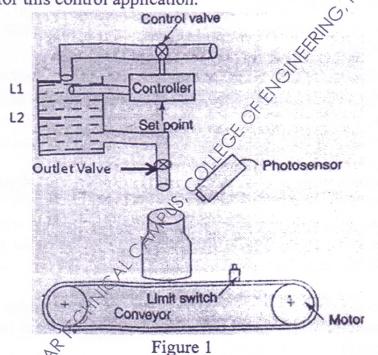
(CBGS) 03 Hrs

[Total Marks 80]

	(2) Atten (3) Figur (4) Assur	rest to right indicate full marks me suitable data if necessary. tions carry usual meaning.	00
*	(5) Notat	tions carry usual meaning.	
	Q.1 (A)	Explain Universal Asynchronous Receiver and Transmitter (UART)	05
		With a neat block diagram explain the architecture of a	05
		Write short note on supervisory control and data acquisition (SCADA)	05
	(D)	Write short notes on (i) Harmonic drive (ii) Data loggers	05
	Q.2 (A)	With neat sketch explain the constructional feature and working of pressure relief valve used in hydraulic system	05
	(B)	Explain the central theme of velocity profile optimization of DC	05
	(C)	Explain with neat sketch principle of operation of AC induction motor	10
	Q.3(A)	Two double acting pneumatic cylinders A, B are selected for an industrial application. The sequence of movement for piston of the cylinder is proposed as below—	12
		Delay B+ Delay (AB)-	
		Develop the electropneumatic circuit using 5/2 double solenoid as final directional control valves. The piston motions mentioned in bracket is simultaneous.	
	(B)	Explain impedance matching for a part of electromechancial system that consists of transmission of power using motor-gear drive system.	08
		Explain input and output components (typically sensors, actuators	10
	(B)	With neat diagrams illustrate the working of Filter-Regulator- Lubricator (FRL) unit in a pneumatic system.	05
	71/1 (C)	Explain with neat sketch working principle of DC motor	05
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AND TO TO TO		[Turn Over	

- Q.5(A) With schematic representation explain the mechatronic system typically used in robot for firefighting application (typically highlight the selection of motor, sensors and switches. Also discuss

Q.6 (A) A process control system illustrated in Figure 1 is used to fill the bottle and convey the same. The outlet valve is opened to fill the bottle as when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is closed automatically when the limit switch senses the presence is maintained through a control valve. Develop a PLC ladder logic diagram for this control application.



WRO 16025 AND WATER STATE OF THE PROPERTY OF T (B) Write short note on (i) Piezoelectric drive (ii) Voice-coil actuator

10