Unit 2

Design of Three Phase and Single Phase Transformer

Introduction

Constituents of transformer:

- i. Magnetic Circuit
- ii. Electric Circuit
- iii. Dielectric Circuit
- iv. Other accessories

Constructional Details

Constructional Details

- The requirements of magnetic material are,
	- **High permeability**
	- **Low reluctance**
	- **High saturation flux density**

Smaller area under B-H curve

- For small transformers, the laminations are in the form of E,I, C and O as shown in figure
- The percentage of silicon in the steel is about 3.5. Above this value the steel becomes very brittle and also very hard to cut

Transformer Core

Core type Construction Shell Type Construction

- It relates the rated kVA output to the area of core & window
- The output kVA of a transformer depends on,
	- Flux Density (B) related to Core area
	- Ampere Turns (AT) related to Window area
- Window Space inside the core to accommodate primary & secondary winding

Let,

- T- No. of turns in transformer winding
- f Frequency of supply

Induced EMF/Turn, $E_t=E/T=4.44f\varphi_m$

 Window in a 1φ transformer contains one primary & one secondary winding.

Window Space factor, $K_w = \frac{\text{Conductor area in Window}}{\text{Total area of Window}}$ Window Space factor, $K_w = \frac{A_c}{A}$ \therefore Conductor area in window, A_c = K_w A_w \rightarrow (2) Current Density (δ) is same in both the windings $\delta = \frac{I_p}{a_p} = \frac{I_s}{a_s} \rightarrow (3)$

Output Equation of Transformer $\therefore a_p = \frac{I_p}{\delta} \; ; a_s = \frac{I_s}{\delta}$

If we neglect magnetizing MMF, then $(AT)_{primary} = (AT)_{secondary}$ \therefore AT=I_pT_p=I_sT_s \rightarrow (4)

Total Cu. Area in window, Ac=Cu.area of pry wdg + Cu.area of sec wdg

$$
=T_p a_p + T_s a_s
$$

\n
$$
T_p a_p + T_s a_s
$$

\n
$$
T_p \frac{I_p}{\delta} + T_s \frac{I_s}{\delta}
$$

\n
$$
\frac{1}{\delta} \Big[T_p I_p + T_s I_s \Big]
$$

\n
$$
\frac{1}{\delta} \Big[AT + AT \Big] = \frac{2AT}{\delta} \rightarrow (5)
$$

Therefore, equating (2) & (5),

$$
K_w A_w = \frac{2AT}{\delta}
$$

$$
AT = \frac{1}{2} K_w A_w \delta \rightarrow (6)
$$

kVA rating of 1φ transformer is given by,

$$
Q = V_p I_p \times 10^{-3} \approx E_p I_p \times 10^{-3}
$$

= $\frac{E_p}{T_p} T_p I_p \times 10^{-3}$ from (1), $E_t = \frac{E}{T}$
= $E_t \Box A T \times 10^{-3} \rightarrow (6)$
= 4.44 $f \varphi_m \cdot \frac{1}{2} K_w A_w \delta \times 10^{-3}$
= 2.22 $\Box f \varphi_m \Box K_w A_w \delta \times 10^{-3}$

We know that,

$$
B_m = \frac{\varphi_m}{A_i} \text{ and } \varphi_m = B_m A_i
$$

: $Q = 2.22 \text{ if } B_m A_i A_w K_w \delta \times 10^{-3} kVA$

w

Three phase transformer:

Each window has 2 primary & 2 Secondary windings.

 $\sqrt{2}$

Total Cu. Area in the window is given by,

$$
A_c = 2T_p a_p + 2T_s a_s
$$

\n
$$
A_c = \frac{4AT}{\delta} \rightarrow (7)
$$

\nCompare (2) \wedge (7), $\Rightarrow \frac{4AT}{\delta} = K_w A$
\n
$$
AT = \frac{K_w A_w \delta}{4}
$$

kVA rating of 3φ transformer,

$$
Q=3 E_p I_p \times 10^{-3}
$$

= $3 \frac{E_p}{T_p} T_p I_p \times 10^{-3}$
= E_f \Box 417 × 10⁻³
= 3 × 4.44 × $f \varphi_m$. $\times \frac{1}{4} K_w A_w \delta \times 10^{-3}$
= 3.33 f B_m A_i A_w K_w $\delta \times 10^{-3}$ kVA

EMF per Turn

• Design of Xmer starts with the section of EMF/turn.

Let, Ratio of Specific magnetic loading to Electric loading

$$
\{\nexists f\} r = \frac{\varphi_m}{AT}
$$
\n
$$
Q = V_p I_p \times 10^{-3}
$$
\n
$$
= 4.44 f \varphi_m T_p I_p \times 10^{-3}
$$
\n
$$
= 4.44 f \varphi_m (AT) \times 10^{-3}
$$
\n
$$
= 4.44 f \varphi_m \frac{\varphi_m}{r} \times 10^{-3}
$$
\n
$$
\varphi_m^2 = \frac{Q \cdot r}{4.44 f \times 10^{-3}} = \frac{Q \cdot r \times 10^3}{4.44 f}
$$
\n
$$
\varphi_m = \sqrt{\frac{Q \cdot r \times 10^3}{4.44 f}}
$$

EMF per Turn

$$
w.k.t, E_t = 4.44 f \varphi_m
$$

=4.44 f $\sqrt{\frac{Q \cdot r \times 10^3}{4.44 f}} = \sqrt{4.44 f} \cdot \sqrt{4.44 f} \cdot \sqrt{r \times 10^3} \cdot \frac{\sqrt{Q}}{\sqrt{4.44 f}}$
= $\sqrt{4.44 f \cdot r \times 10^3} \cdot \sqrt{Q}$
where, $K = \sqrt{4.44 f \cdot r \times 10^3}$ $E_t = K \cdot \sqrt{Q}$

 K depends on the type, service condition & method of construction of transformer.

EMF per Turn

Optimum Design

- Transformer may be designed to make one of the following quantities as minimum.
	- Total Volume
	- Total Weight
	- **Total Cost**
	- Total Losses
- In general, these requirements are contradictory & it is normally possible to satisfy only one of them.
- All these quantities vary with $r = \frac{\varphi_m}{r}$

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Optimum Design Design for Minimum Cost

Let us consider a single phase transformer. $Q=2.22 \cdot f B_{m} A A_{m} K_{m} \delta \times 10^{-3}$ kVA $Q=2.22 \cdot f B_m A A_c \delta \times 10^{-3}$ kVA $[A_c = K_w A_v]$

Assuming that flux & current densities are constant, $A_c.A_i -$ **Constant**

Let, In optimum design, it aims to determining the minimum value of total cost. $r = \frac{\varphi_m}{\sqrt{m}}$ AT $\varphi_m = B_m A_i$

$$
AT = \frac{1}{2}K_w A_w \delta = \frac{A_c \delta}{2}
$$

Optimum Design

Design for Minimum Cost

- Let, C_t Total cost of transformer active materials
- C_i Cost of iron
- $\mathrm{C_{c}}$ Cost of conductor
- p_i Loss in iron/kg (W)
- p_c Loss in Copper/kg (W)
- l_i Mean length of flux path in iron(m)
- L_{mt} Mean length of turn of transformer winding (m)
- G_i Weight of active iron (kg)
- G_c Weight of Copper (kg)
- g_i Weight/m³ of iron
- $\rm g_c$ Weight/m 3 of Copper

$$
C_t = C_i + C_c = c_i G_i + c_c G_c
$$

Optimum Design Design for Minimum Cost

 $r = \frac{B_m A_i}{A_c \delta} = \frac{2 B_m A_i}{A_c \delta}$ $r = \frac{A_i}{A_c} \frac{2 B_m}{\delta}$ $\frac{A_i}{A_c} = \frac{\delta}{2\,B_m} \cdot r = \beta \quad \rightarrow (2\,)$

β is the function of r alone [δ & $B_m -$ Constant] From (1) & (2),

$$
A_i = M \sqrt{\beta} \quad \wedge A_c = \frac{M}{\sqrt{\beta}} \qquad \qquad [\because A_c A_i = M^2]
$$

Optimum Design Design for Minimum Loss and Maximum Efficiency

Total losses at full load = P_i + P_c

At any fraction x of full load, total losses = $P_i + x^2 P_c$

If output at a fraction of *x* of full load is *xQ.* Efficiency, $\eta_x = \frac{\mathbf{xQ}}{\mathbf{xQ} + P_x + x^2 P_x}$ Condition for maximum efficiency is, $\frac{d\eta_x}{dx} = 0$ $\frac{d\eta_x}{dx} = \frac{\left(\mathbf{XQ} + P_i + x^2 P_c\right)\mathbf{Q} - \left(Q + 2\mathbf{X}P_c\right)\mathbf{XQ}}{\left(\mathbf{XQ} + P_i + x^2 P_c\right)^2} = 0$ $\left(\mathbf{XQ} + P_i + x^2 P_c\right)Q = \left(Q + 2xP_c\right)\mathbf{XQ}$ $\left(\mathbf{XQ} + P_i + x^2 P_c\right) = \left(Q + 2\mathbf{X}P_c\right)\mathbf{x}$ $\mathbf{XQ} + P_i + x^2 P_i = \mathbf{XQ} + x^2 P_i + x^2 P_i$ $P_i = x^2 P_c$

Optimum Design

Design for Minimum Cost

 $C_i = c_i g_i l_i A_i + c_c g_c L_{\text{mt}} A_c$ where. $c \wedge c$ = specific costs of iron and copper respectively. $C_t = c_i g_i l_i M \sqrt{\beta} + c_c g_c L_{\text{int}} \frac{M}{\sqrt{\beta}}$

Differentiating C_t with respect to β ,

$$
\frac{d}{d\beta}C_t = \frac{1}{2}c_i g_i l_i M(\beta)^{-1/2} - \frac{1}{2}c_c g_c L_{\text{int}} M\beta^{-3/2}
$$

For minimum cost, $\frac{d}{dx}C=0$

$$
d\beta
$$

\n
$$
\frac{1}{2}c_i g_i l_i M(\beta)^{-1/2} = \frac{1}{2}c_c g_c L_{\text{int}} M\beta^{-3/2}
$$

\n
$$
c_i g_i l_i = c_c g_c L_{\text{int}} \frac{A_c}{A_i}
$$

Optimum Design

Design for Minimum Cost $c_i g_i l_i A_i = c_e g_c L_{\text{mt}} A_c$

$$
c_i G_i = c_c G_c
$$

$$
C_i = C_c
$$

Hence for minimum cost, the cost of iron must be equal to the cost of copper.

Similarly,

For minimum volume of transformer,

$$
G_i g_i {=} G_c g_c \textit{ or } G_i G_c {=} g_i g_c
$$

Volume of iron = Volume of Copper

For minimum weight of transformer, Weight of iron = Weight of Conductor

For minimum loss, Iron $loss = 12R$ loss in conductor

$$
P_i = x^2 P_c
$$

 $G_i = G_c$

Optimum Design Design for Minimum Loss and Maximum Efficiency

Variable losses = Constant losses

$$
P_i P_c = \frac{p_i G_i}{p_c G_c}
$$

$$
x^2 = \frac{p_i G_i}{p_c G_c} \quad or \quad \frac{G_i}{G_c} = x^2 \frac{p_c}{p_i}
$$

for maximum efficiency

Design of Core

- Core type transformer : Rectangular/Square /Stepped cross section
- Shell type transformer : Rectangular cross section

Design of Core Square & Stepped Core

- Used when circular coils are required for high voltage distribution and power transformer.
- Circular coils are preferred for their better mechanical strength.

• Circle representing the inner surface of the tubular form carrying the $_{27}$ windings (Circumscribing Circle)

Design of Core Square & Stepped Core

- Diameter of Circumscribing circle is larger in Square core than Stepped core with the same area of cross section.
- Thus the length of mean turn(L_{mt}) is reduced in stepped core and reduces the cost of copper and copper loss.
- However, with large number of steps, a large number of different sizes of laminationsare used.

Design of Core Square Core

Gross core area includes insulation area order Net core area excludes insulation area Area of Circumscribing circle $\frac{\pi}{4}d^2$

Ratio of net core area to Area of Circumscribing circle is

$$
\frac{0.45 d^2}{\frac{\pi}{4}d^2} = 0.58
$$

Ratio of gross core area to Area of Circumscribing circle is $\frac{0.5 d^2}{2} = 0.64$ 29 $\frac{\pi}{d^2}$

Design of Core Square Core

Let, d - diameter of circumscribing circle

 a – side of square Diameter, $d = \sqrt{a^2 + a^2} = \sqrt{2a^2} = \sqrt{2} \cdot a$ $a = \frac{d}{\sqrt{2}}$

Gross core area, $A_{gi} = Area \ of \ square = a^2 = \left(\frac{d}{\sqrt{2}}\right)^2$ $A_{\rm ej} = 0.5d^2$ Let the stacking factor, $S_f=0.9$ Net core area, $A_i = 0.9 \times 0.5 d^2 = 0.45 d^2$

Design of Core Square Core

Useful ratio in design – Core area factor,

$$
K_C = \frac{\text{Net Core area}}{\text{Square of Circumscribing Circle}}
$$

= $\frac{A_i}{d^2} = \frac{0.45 d^2}{d^2} = 0.45$

Design of Core Stepped Core or Cruciform Core

Let,a – Length of the rectangle

b – breadth of the rectangle

d – diameter of the circumscribing circle and diagonal of the rectangle.

 θ – Angle b/w the diagonal and length of the

- The max. core area for a given 'd' is obtained by the max value of θ
- For max value of ' θ ',
 $\frac{dd_{gi}}{g_i}$ o

• From the figure,
$$
\cos \theta = \frac{a}{d} \Rightarrow \therefore a = d \cos \theta
$$

 $\sin \theta = \frac{b}{d} \Rightarrow \therefore b = d \sin \theta$

Design of Core Stepped Core or Cruciform Core

Two stepped core can be divided in to 3 rectangles.

Referring to the fig shown,

Gross core area,
$$
A_{gi} = ab + \left(\frac{a-b}{2}\right) b + \left(\frac{a-b}{2}\right) b
$$

= $ab + \frac{2(a-b)}{2} b$
= $ab + ab - b^2 = 2ab - b^2$

On substituting 'a' and 'b' in the above equations,

$$
A_{gi} = 2(d\cos\theta)(d\sin\theta) - (d\sin\theta)
$$

\n
$$
A_{gi} = 2d^2\cos\theta\sin\theta - d^2\sin^2\theta
$$

\n
$$
A_{gi} = d^2\sin 2\theta - d^2\sin^2\theta
$$

For max value of θ ,

$$
\frac{dA_{gi}}{d\theta} = 0
$$

Design of Core
\n**Steped Care or Crueiform Core**
\ni.e.,
$$
\frac{dA_{gi}}{d\theta} = d^2 2\cos 2\theta - d^2 (2\sin \theta \cos \theta) = 0
$$

\n $d^2 2\cos 2\theta = a^2 (2\sin \theta \cos \theta)$
\n $2\cos 2\theta = \sin 2\theta$
\n $\frac{\sin 2\theta}{\cos 2\theta} = 2$
\n $\tan 2\theta = 2$
\n $2\theta = \tan^{-1}(2)$
\n $\theta = \frac{1}{2} \tan^{-1}(2) = 31.72^\circ$

Therefore, if the $\theta = 31.72^{\circ}$, the dimensions 'a' & 'b' will give maximum area of core for a specified 'd'.

$$
\cos \theta = \frac{a}{d} \Rightarrow \therefore a = d \cos \theta \Rightarrow a = d \cos (31.72^{\circ}) = 0.85 d
$$

$$
\sin \theta = \frac{b}{d} \Rightarrow \therefore b = d \sin \theta \Rightarrow b = d \sin (31.72^{\circ}) = 0.53 d
$$

Design of Core Stepped Core or Cruciform Core

Gross core area, $A_{gi} = 2ab - b^2$ A_{ei} = 2(0.85 d)(0.53 d) – (0.53 d)² $A_{\varphi i} = 0.618 d^2$ Let stacking factor, $S_f = 0.9$, Net core area, A_i = Stacking factor X Gross Core area $A_i = 0.9 \times 0.618 d^2 = 0.56 d^2$ Net core area
Area of Circumscribing circle $\frac{0.56 d^2}{\frac{\pi}{4} d^2} = 0.71$ The ratios, $= \frac{0.618 d^2}{2} = 0.79$ 35 Gross core area Area of Circumscribing circle $rac{\pi}{4}d^2$

Design of Core Stepped Core or Cruciform Core

Core area factor,

 $K_c = \frac{\text{Net Core area}}{\text{Square of Circumscribing Circle}}$ $=\frac{A_i}{d^2}=\frac{0.56 d^2}{d^2}=0.56$

Ratios of Multi-stepped Cores,

Transformer Core

Stepped Core Construction

Transformer Core

Core Type

Shell Type

Overall Dimensions

Single phase Core Type

Overall Dimensions

Single phase Shell Type

Overall Dimensions

Thee phase Core Type

Design of Winding

- **→** Transformer windings: HV winding & LV winding
- **→ Winding Design involves:**
	- \rightarrow Determination of no. of turns: based on kVA rating & EMF per turn
	- Area of cross section of conductor used: Based on rated current and Current density
- \rightarrow No. of turns of LV winding is estimated first using given data.
- \rightarrow Then, no. of turns of HV winding is calculated to the voltage rating. No. of turns in LV winding, $T_{LV} = \frac{V_{LV}}{E_{A}} (or) \frac{AT}{I_{UV}}$ where, V_{LV} = Rated voltage of LV winding I_{IV} Rated Current of LV winding

Design of Winding

No. of turns in HV winding, $T_{HV} = T_{LV} \times \frac{V_{HV}}{V_{UV}}$ where, V_{H} – Rated voltage of HV winding

Transformer Winding

 Types of transformer windings are, Concentric Sandwich Disc **So Cross over** Helical

Constructional Details

Transformer Winding

Transformer Winding

Insulations

 \bigoplus Dry type Transformers: Varnish Enamel Large size Transformers: Unimpregnated paper **W** Cloths Immersed in Transformer oil – insulation & coolent

Comparison between Core & Shell Type

Classification on Service

Transformer Core

Core Type

Shell Type

Cooling of transformers

Temperature rise in plain walled tanks

- Transformer wall dissipates heat in radiation & convection.
- For a temperature rise of 40⁰C above the ambient temperature of 20⁰C, the heat dissipations are as follows:
	- \rightarrow Specific heat dissipation by radiation, λ_{rad} =6 W/m².^oC .
	- \rightarrow Specific heat dissipation by convection, $\lambda_{\text{conv}} = 6.5 \text{ W/m}^2$. O .
	- \rightarrow Total heat dissipation in plain wall 12.5 W/m²⁰C .

S_t – Heat dissipating surface

→ Heat dissipating surface of tank : Total area of vertical sides+ One half area of top cover(Air cooled) (Full area of top cover for oil cooled)

Cooling of transformers Transformer Oil as Cooling Medium

 \rightarrow Specific heat dissipation due to convection is,

$$
\lambda_{conv} = 40.3 \left(\frac{\theta}{H} \right)^{14} W/m^2. \ ^0C
$$

where, θ - Temperature difference of the surface relative to oil, ${}^{0}C$ H – Height of dissipating surface, m

 \rightarrow The average working temperature of oil is 50-60 °C.

 \rightarrow For $\theta = 20^{\circ} C \wedge H = 0.5$ to 1 m, λ_{conv} = 80 to 100 W/m².⁰ C.

The value of the dissipation in air is 8 W/m^{2 o}C. i.e, 10 times less than oil. .

- Cooling tubes increases the heat dissipation
- Cooling tubes mounted on vertical sides of the transformer would not proportional to increase in area. Because, the tubes prevents the radiation from the tank in screened surfaces.
- But the cooling tubes increase circulation of oil and hence improve the convection
- Circulation is due to effective pressure heads
- Dissipation by convection is equal to that of 35% of tube surface area. i. e., 35% tube area is added to actual tube area.

Let, Dissipating surface of tank $-S_{t}$

Dissipating surface of tubes $- X S_t$

Loss dissipated by surface of the tank by radiation and convection =

 $(6+6.5)S_t = 12.5S_t$

Loss dissipated by tubes by convection Total loss dissipated by walls and tubes

 $6.5 \times \frac{135}{100} \times XS_{t} = 8.8XS_{t}$ 12.5S_t + 8.8XS_t = (12.5 + 8.8X) S_t \rightarrow (1)

Actual total area of tank walls and tubes = $S_t + XS_t = S_t(1+X)$

Totalarea of cooling tubes = $\frac{1}{8.8} \left(\frac{P_i + P_c}{\theta S_t} - 12.5 \right) S_t = \frac{1}{8.8} \left(\frac{P_i + P_c}{\theta} - 12.5 S_t \right) \rightarrow (5)$

- Let, l_{t} Lengthof tubes
	- d_{t} Diameterof tubes
- \therefore Surfacearea of tubes = π d,l,

Totalnumberof tubes, $n_t = \frac{\text{Totalarea of tubes}}{\text{Area of each tube}}$

$$
n_{t} = \frac{1}{8.8\pi d_{t}l_{t}} \left(\frac{P_{i} + P_{c}}{\theta} - 12.5S_{t}\right) \rightarrow (6)
$$

- Standard diameter of cooling tube is 50mm & length depends on the height of the tank.
- \rightarrow Center to center spacing is 75mm.

- \rightarrow Dimensions of the tank:
	- Let, C_1 Clearance b/w winding and tank along width
	- C_2 Clearance b/w winding and tank along length
	- C_3 Clearance b/w the transformer frame and tank at the bottom
	- C4 Clearance b/w the transformer frame and tank at the top
	- D_{oc} Outer diameter of the coil.
	- Width of the tank, $W_T = 2D + D_{oc} + 2C_1$ (For 3 ϕ Transformer)

 $= D + D_{oc} + 2 C_1$ (For 1 ϕ Transformer)

Length of the tank, $L_T = D_{oc} + 2 C_2$

Height of the tank, $H_T=H+C_3+C_4$

- \rightarrow Clearance on the sides depends on the voltage $\&$ power ratings.
- \rightarrow Clearance at the top depends on the oil height above the assembled transformer & space for mounting the terminals and tap changer.
- \rightarrow Clearance at the bottom depends on the space required for mounting the frame.

- A 250 kVA , 6600/400 V , 3 PHASE CORE TYPE TRANSFORMER HAS A TOTAL LOSS OF 4800 W at full load. The transformer tanks is 1.25 m in height and 1m * 0.5 m in plan. Design a suitable scheme for tubes if the average temperature rise is to be limited to 35 degree c. The diameter of tube is 50 mm and are spaced 75 mm from each other . The average heights of tubes is 1.05 m. specific heat dissipation due to radiation and convection is respectively 6 and 6.5 W/m2- deg. C
- \rightarrow Assume that convection is improved by 35 per cent due to provision of tubes.

Solution. Area of plane tank $S_t = 2(1 + 0.5) \times 1.25 = 3.75$ m² Let the tube area be xSt . : Total dissipating surface = $(1 + x) S_t = 3.75 (1 + x)$ Specific loss dissipation = $\frac{4800}{3.75(1+x) \times 35} = \frac{36.5}{1+x}$ W/m² – °C From Eqn. 5.98 loss dissipated = $\frac{12.5 + 8.8x}{1 + x}$ W/m² - °C $\frac{12.5 + 8.8x}{1 + x} = \frac{36.5}{1 \times x}$ or $x = 2.73$ Area of tubes = $2.73 \times 3.75 = 10.23$ m². Wall area of each tube = $\pi d_t l_t = \pi \times 0.05 \times 1.05 = 0.165$ m². \therefore Total number of tubes to be provided = 10.23/0.165 = 62.

No-load Current of Transformer:

Magnetizing Component

Depends on MMF required to establish required flux

Loss Component

Depends on iron loss

No-load current of Single phase Transformer

Total Length of the core $= 2l_c$

Total Length of the yoke = 2*l y*

Here, l_c =H_w=Height of Window

l y = Ww=Width of Window

MMF for core=MMF per metre for max. flux density in core X Total length of Core = at_{c} X 2*l*_c = 2 at_{c} *l*_c

MMF for yoke=MMF per meter for max. flux density in yoke X Total length of yoke $=$ $at_y X 2l_y = 2 at_y l_y$

Total Magnetizing MMF, AT_0 =MMF for Core+MMF for Yoke+MMF for joints $=$ 2 $at_c l_c + 2 at_y l_y + MMF$ for joints

The values of at_c & at_y are taken from B-H curve of transformer steel.

No-load current of Single phase Transformer

Max. value of magnetizing current=AT₀/T_p If the magnetizing current is sinusoidal then, RMS value of magnetizing current, $I_m = AT_0 / \sqrt{2}T_p$ If the magnetizing current is not sinusoidal, RMS value of magnetizing current, $I_m = AT_0/K_{pk}T_p$ The loss component of no-load current, $I_i = P_i / V_p$ Where, P_i – Iron loss in Watts V_p – Primary terminal voltage Iron losses are calculated by finding the weight of cores and yokes. Loss per kg is given by the manufacturer. No-load current, *2* $I_0 = \sqrt{I_m^2 + I_l^2}$ \overline{O}

Total Magnetizing MMF, AT_0 =MMF for Core+MMF for Yoke+MMF for joints $= 3$ at_c l_c +2 at_y l_y +MMF for joints

Total Magnetizing MMF, $AT_{0 per phase}$ =MMF for Core+MMF for Yoke+MMF for joints

 $=$ $(3at_c l_c + 2 at_y l_y + MMF$ for joints)/3